



AXIOMTEK

Q7M100 and Q7B100

BSP

User's Manual



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ESD Precautions

Computer boards have integrated circuits sensitive to static electricity. To prevent chipsets from electrostatic discharge damage, please take care of the following jobs with precautions:

- Do not remove boards or integrated circuits from their anti-static packaging until you are ready to install them.
- Before holding the board or integrated circuit, touch an unpainted portion of the system unit chassis for a few seconds. It discharges static electricity from your body.
- Wear a wrist-grounding strap, available from most electronic component stores, when handling boards and components.

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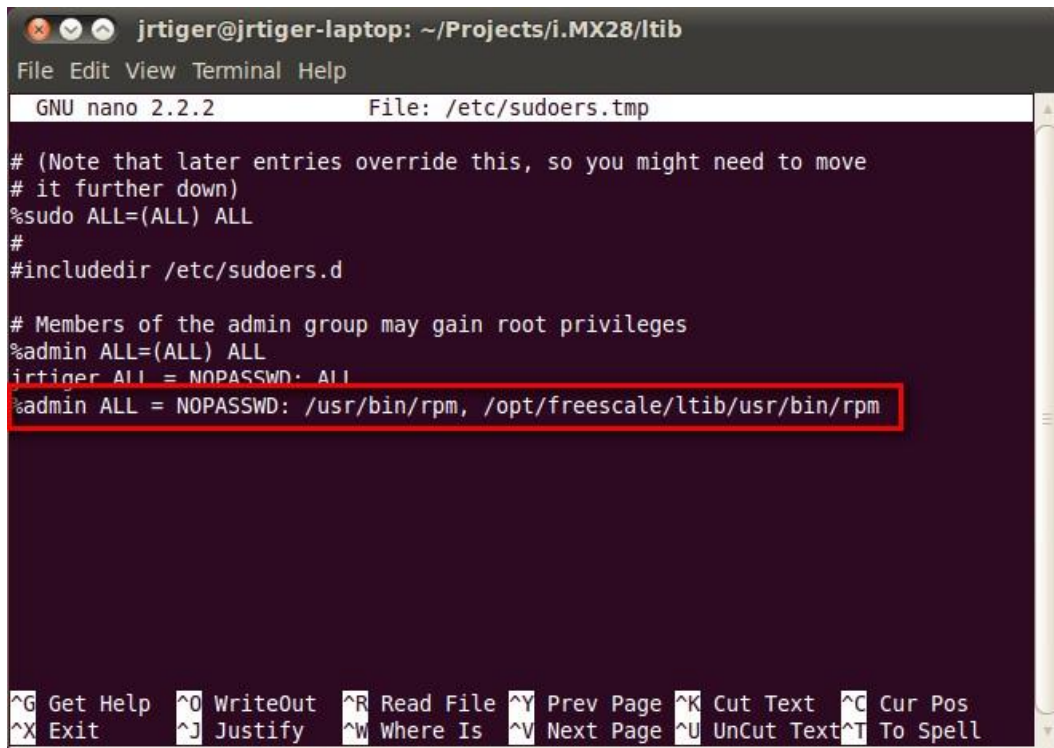
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Chapter 1

Host Development System Installation

1.1 Install Host System

1. Download Ubuntu 10.04 LTS iso image.
2. Install Ubuntu 10.04.
3. Sudoers:
To edit the sudoer's file, please run 'sudo visudo'. At the end of the sudoers file, add the following line; which is needed for using LTIB. This assumes that all your developers have administrator privileges on this host. If that is not the case, add a similar line for each user.



```
jrtiger@jrtiger-laptop: ~/Projects/i.MX28/ltib
File Edit View Terminal Help
GNU nano 2.2.2 File: /etc/sudoers.tmp
# (Note that later entries override this, so you might need to move
# it further down)
%sudo ALL=(ALL) ALL
#
#include_dir /etc/sudoers.d
# Members of the admin group may gain root privileges
%admin ALL=(ALL) ALL
jrtiger ALL = NOPASSWD: ALL
%admin ALL = NOPASSWD: /usr/bin/rpm, /opt/freescale/ltib/usr/bin/rpm
^G Get Help ^O WriteOut ^R Read File ^Y Prev Page ^K Cut Text ^C Cur Pos
^X Exit ^J Justify ^W Where Is ^V Next Page ^U UnCut Text ^T To Spell
```

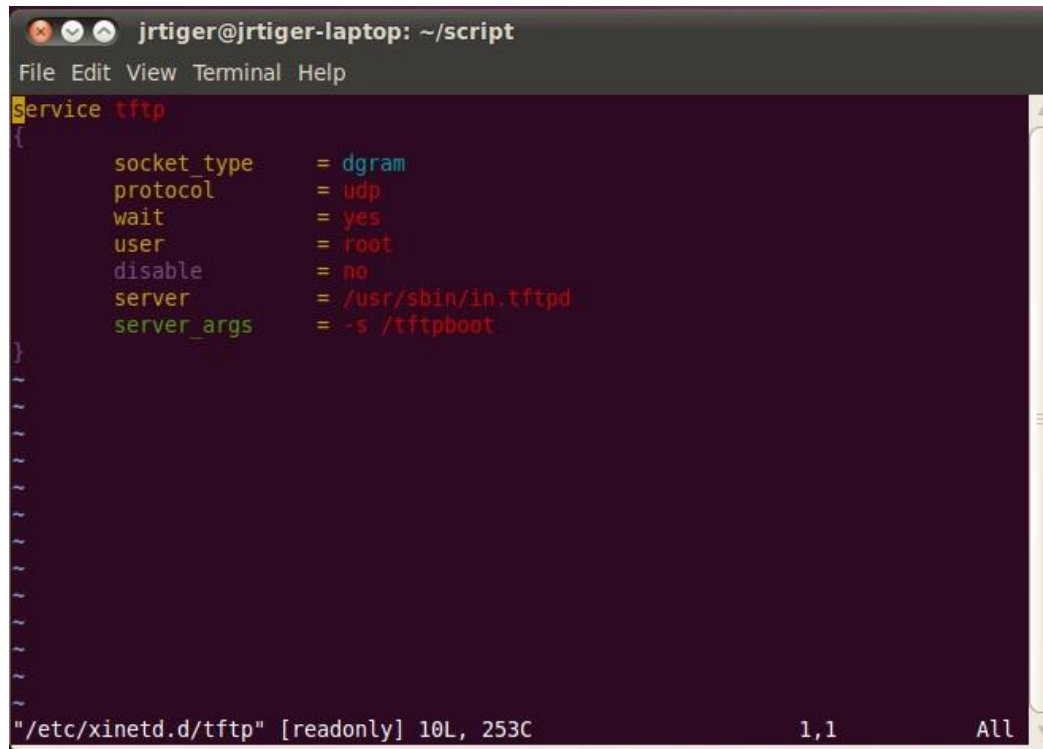
4. Install host packages needed by LTIB as follows:

```
$ sudo aptitude -y install gettext libgtk2.0-dev rpm bison m4 libfreetype6-dev
$ sudo aptitude -y install libdbus-glib-1-dev liborbit2-dev intltool
$ sudo aptitude -y install ccache ncurses-dev zlib1g zlib1g-dev gcc g++ libtool
$ sudo aptitude -y install uuid-dev liblzo2-dev
$ sudo aptitude -y install tcl
```

5. Install and configure TFTP server:

After tftpd installed, configure it by editing `/etc/xinetd.d/tftp`. Change the default export path (it is either `/usr/var/tftpboot` or `/var/lib/tftpboot`) to `.`. Or change the default export path to whatever directory you want to download from. Then reboot the hardware.

```
$ sudo aptitude -y install tftp tftpd xinetd
$ sudo vi /etc/xinetd.d/tftp
```



```
jrtiger@jrtiger-laptop: ~/script
File Edit View Terminal Help
service tftp
{
    socket_type      = dgram
    protocol        = udp
    wait            = yes
    user            = root
    disable         = no
    server          = /usr/sbin/in.tftpd
    server_args     = -s /tftpboot
}

"/etc/xinetd.d/tftp" [readonly] 10L, 253C 1,1 All
```

Then restart the tftp server.

```
$ sudo /etc/init.d/xinetd restart
```

6. Install and configure NFS server:

```
$ sudo aptitude -y install nfs-common nfs-kernel-server portmap
```

To configure nfs server, add lines to `/etc/exports` as follows:

```
/tools/rootfs *(rw, sync, no_root_squash)
```

```
$ sudo vi /etc/exports
```

Create a symbolic link to root filesystem which your Itib build.

```
$ sudo mkdir /tools
```

```
$ sudo ln -s ~/Project/Q7M100/Itib/rootfs /tools/rootfs
```

Then restart the nfs server.

```
$ sudo /etc/init.d/nfs-kernel-server restart
```

1.2 Install LTIB

1. Build your own project folder.
\$ `mkdir -p ~/Project/Q7M100`
2. Extract the source tar ball with the following command:
\$ `tar zxf L2.6.35_10.12.01_SDK_source.tar.gz`
3. Now change directory to the extracted folder and execute the install script. Then you can install it into your own project folder.
\$ `cd L2.6.35_10.12.01_ER_source`
\$ `./install`

```

jrtiger@ubuntu-vm: ~/L2.6.35_10.12.01_ER_source
File Edit View Terminal Help
If the Licensed Software includes software and hardware developed by Global
Locate, Inc. ("Global Locate"), and acquired by Broadcom Corporation, you must
separately obtain rights beyond evaluation and demonstration for the Global
Locate software from Broadcom Corporation.

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If the Licensed Software includes software and hardware developed by Cambridge
Silicon Radio, Inc. ("CSR"), you must separately obtain rights beyond evaluation
and demonstration for the CSR software from CSR.

LAOPT27 Nov 12, 2010

I have read and accept the EULA (yes|no):
yes

The LTIB files are extracted from a tar file which includes the
prefix ltib. After installation you will find LTIB in:
/home/jrtiger/L2.6.35_10.12.01_ER_source/ltib

Where do you want to install LTIB ? (/home/jrtiger/L2.6.35_10.12.01_ER_source)
~/Project/Q7M100

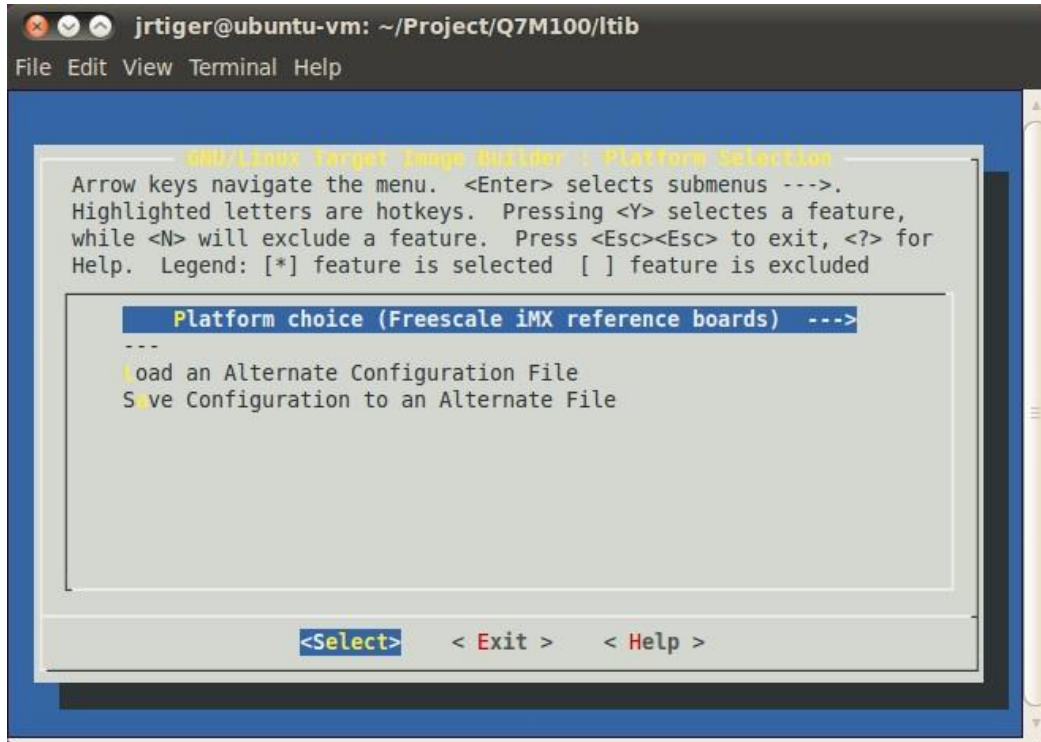
```

4. Configure and build.
This command invokes LTIB with its default behavior of performing a build. Since the installation has not yet been configured, LTIB will present the configuration screen before building. Then, when you exit the configuration screen, LTIB will build the target image. Also, at the very first time you run LTIB on a system, it will build and install a number of host tools that it will place under `/opt/freescale`.

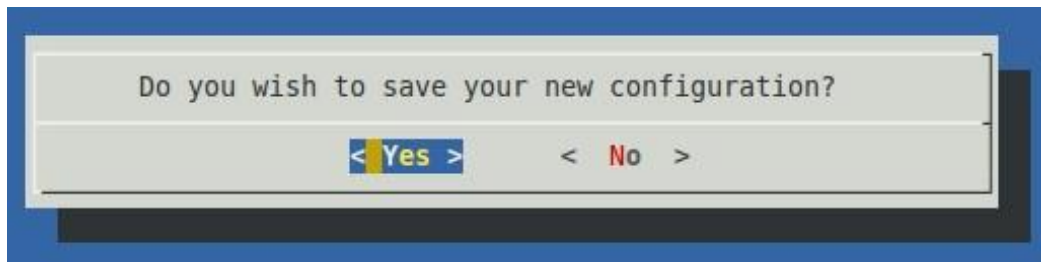
To ask LTIB to show the configuration screen without building afterwards, run this command:

```
$ ./ltib -m config
```

5. First time configuration; please select the iMX platform.



Then save the configuration.



Select the imx28 sub-platform.

```

jrtiger@ubuntu-vm: ~/Project/Q7M100/ltib
File Edit View Terminal Help

FreeScale i.MX development platform
Arrow keys navigate the menu. <Enter> selects submenus --->.
Selection
Use the arrow keys to navigate this window or press the hotkey of
the item you wish to select followed by the <SPACE BAR>. Press
<?> for additional information about this option.

( ) imx25_3stack
( ) imx233/stmp3780
( ) imx27ads
(X) imx28
( ) imx31ads
( ) imx31_3stack
v(+)

<Select> < Help >

<Select> < Exit > < Help >

```

```

jrtiger@ubuntu-vm: ~/Project/Q7M100/ltib
File Edit View Terminal Help

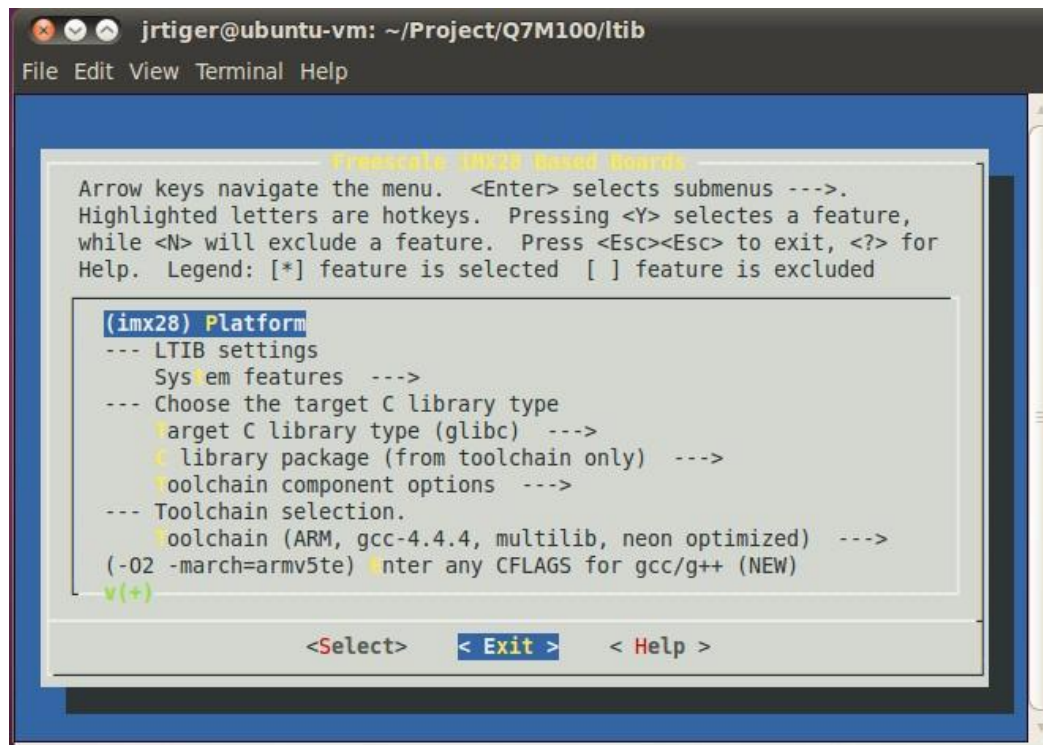
FreeScale i.MX development platform
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing <Y> selects a feature,
while <N> will exclude a feature. Press <Esc><Esc> to exit, <?> for
Help. Legend: [*] feature is selected [ ] feature is excluded

--- Choose the platform type
Selection (imx28) --->
--- Choose the packages profile
Selection (use packages in preconfig (Min profile)) --->
---
Load an Alternate Configuration File
Save Configuration to an Alternate File

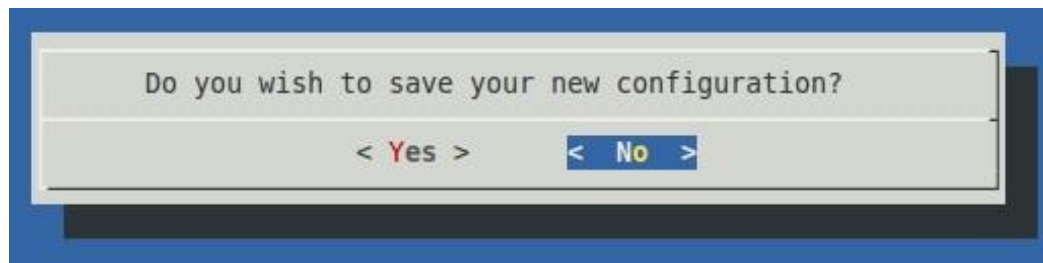
<Select> < Exit > < Help >

```

Exit the sub-platform selection screen and save the configuration. This will bring you to the main LTIB configuration screen.



Just exit without saving main LTIB configuration.



6. Create and patch Q7M100 kernel.
Create the local kernel folder.
\$ mkdir -p ~/Project/Q7M100/kernel

Extract kernel source to this folder.
\$ tar jxf /opt/freescale/pkgs/linux-2.6.35.3.tar.bz2 -C ~/Project/Q7M100/kernel

Extract i.MX platform patches to kernel source folder.
\$ tar jxf /opt/freescale/pkgs/linux-2.6.35.3-imx_10.12.01.bz2 -C
~/Project/Q7M100/kernel/linux-2.6.35.3

Enter the kernel source folder and patch the patches.
\$ cd ~/Project/Q7M100/kernel/linux-2.6.35.3/
\$./patches/patch-kernel.sh

Patch the Q7M100 patches which you can copy from our BSP package.
\$ patch -p1 < ~/patch-2.6.35.3-Q7M100-013.patch

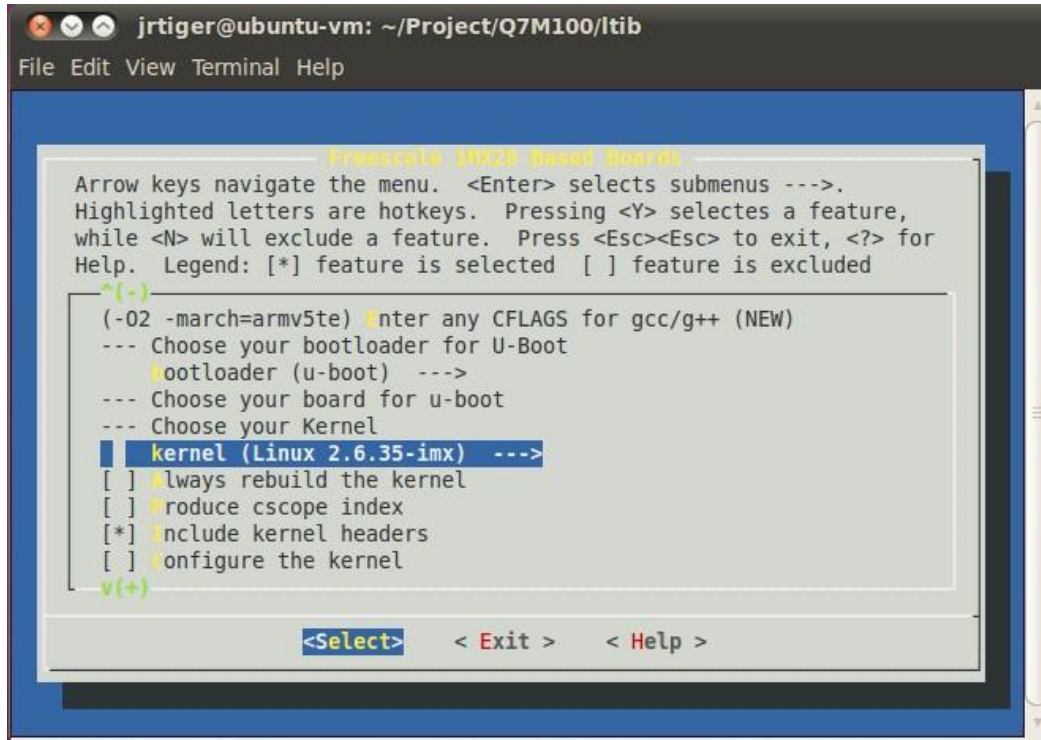
Return to `~/Project/Q7M100/kernel` folder and make a symbolic link to kernel source folder.

```
$ cd ~/Project/Q7M100/kernel
$ ln -s linux-2.6.35.3 linux
```

7. Reconfigure LTIB main setting to build kernel to local Linux directory.

```
$ cd ~/Project/Q7M100/ltib
$ ./ltib -m config
```

Select kernel setting.

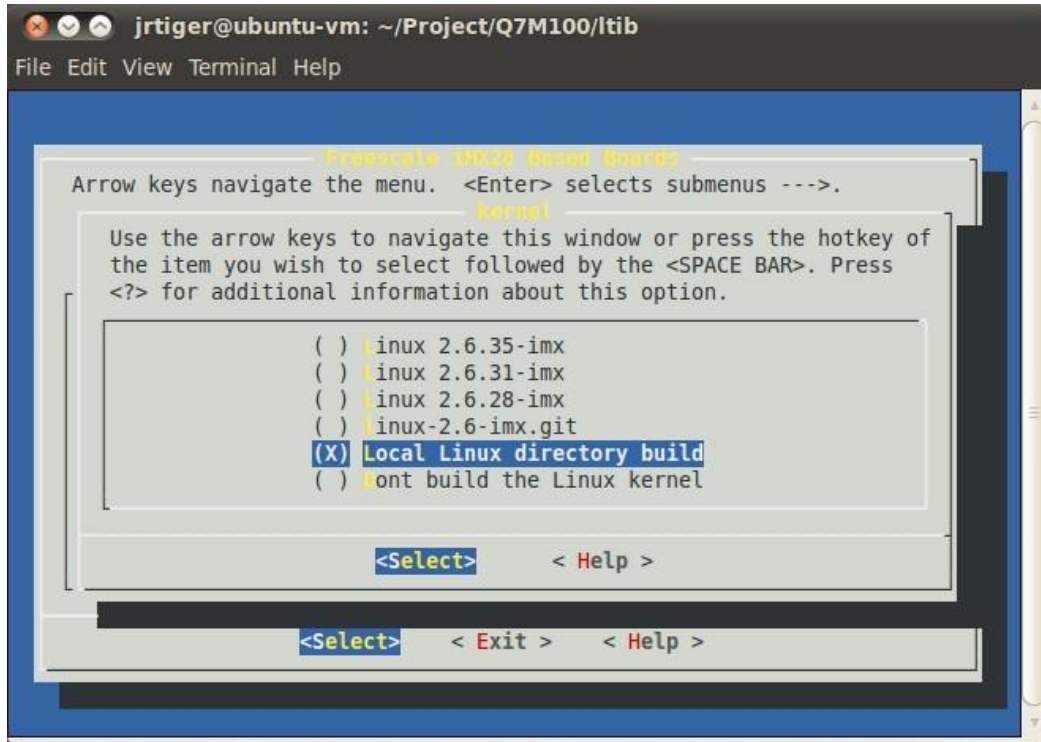


```
jrtiger@ubuntu-vm: ~/Project/Q7M100/ltib
File Edit View Terminal Help

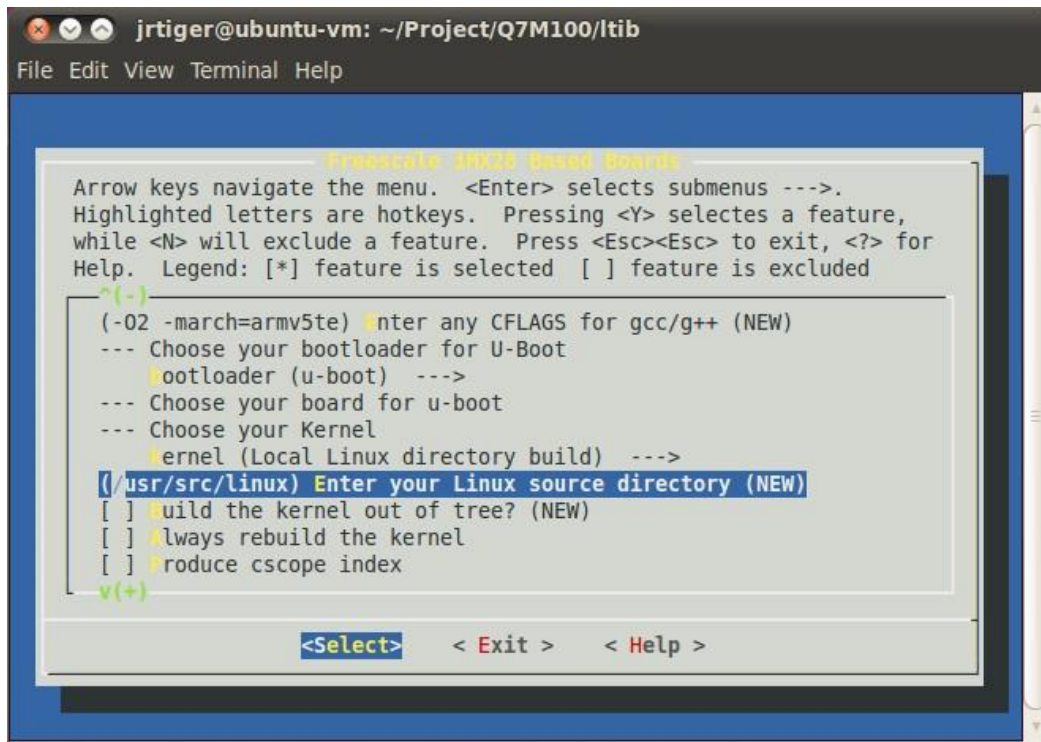
Freescale iMX2D Based Boards
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing <Y> selects a feature,
while <N> will exclude a feature. Press <Esc><Esc> to exit, <?> for
Help. Legend: [*] feature is selected [ ] feature is excluded
^(-)
(-O2 -march=armv5te) Enter any CFLAGS for gcc/g++ (NEW)
--- Choose your bootloader for U-Boot
  bootloader (u-boot) --->
--- Choose your board for u-boot
--- Choose your Kernel
  kernel (Linux 2.6.35-imx) --->
  [ ] Always rebuild the kernel
  [ ] Produce cscope index
  [*] Include kernel headers
  [ ] Configure the kernel
v(+)

<Select>  < Exit >  < Help >
```

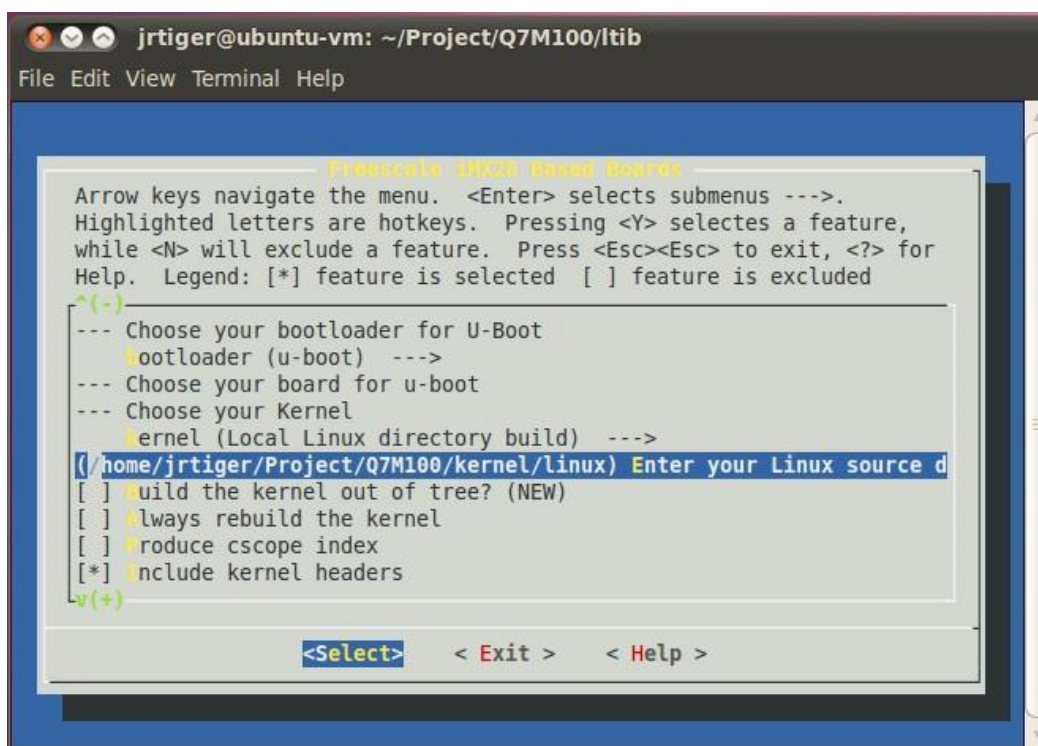
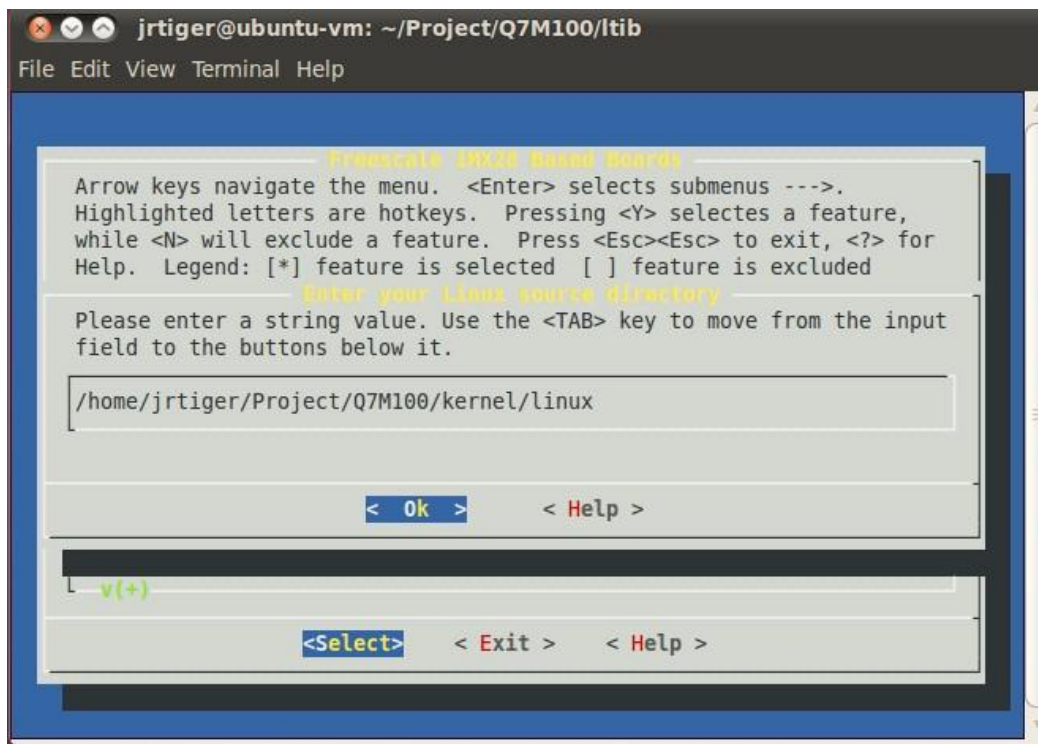
Select Local Linux directory build.



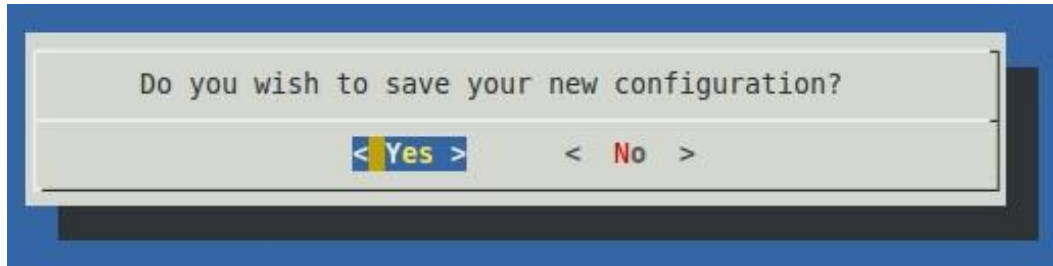
Then enter new linux source directory.



Enter your own linux kernel source folder.



Finally save the configuration.



8. Options :

Adding iMX28 Multimedia codecs support:

Extract codec file.

```
$ tar zxf IMX_MMCODECS_10.12.tar.gz
```

Copy all tar.gz file to /opt/freescale/pkgs folder.

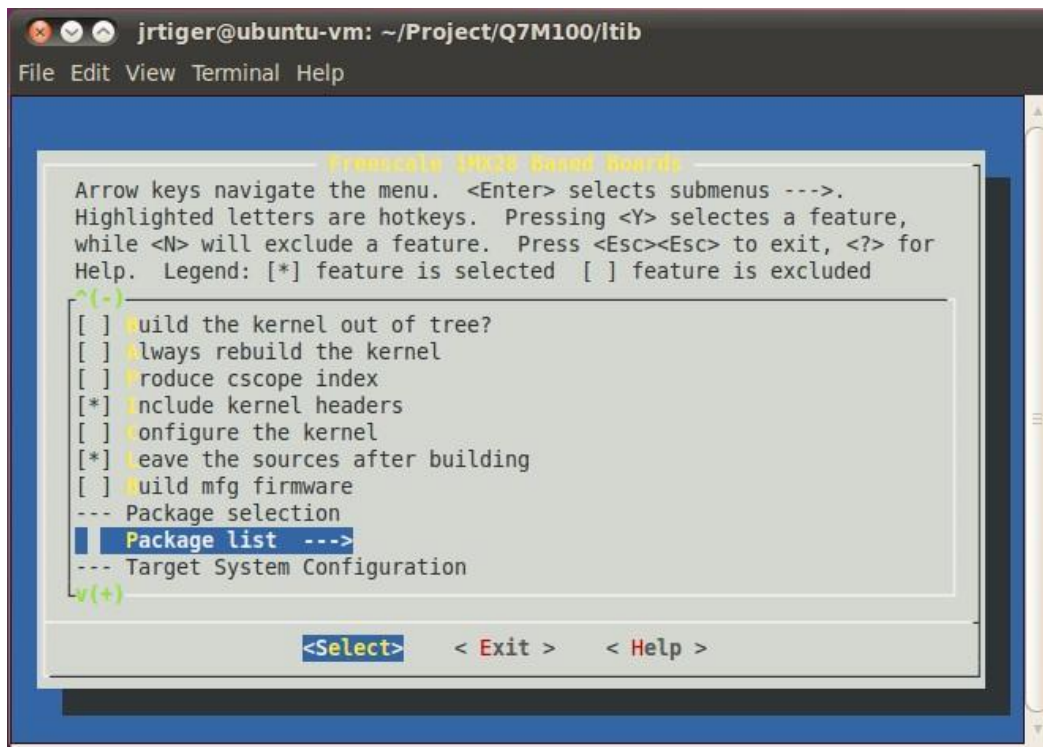
```
$ cp IMX_MMCODECS_10.12/*.tar.gz /opt/freescale/pkgs/
```

Then reconfigure LTIB main setting.

```
$ cd ~/Project/Q7M100/ltib
```

```
$ ./ltib -m config
```

Select Package list.



Select Freescale Multimedia Plugins/Codecs.

```

jrtiger@ubuntu-vm: ~/Project/Q7M100/ltib
File Edit View Terminal Help

Package List
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing <Y> selects a feature,
while <N> will exclude a feature. Press <Esc><Esc> to exit, <?> for
Help. Legend: [*] feature is selected [ ] feature is excluded
*(-)
[noinitrd console=ttyAM0,115200 root=/dev/mmcblk0p3 rw rootwait ip=no
noinitrd console=ttyAM0,115200 ubi.mtd=1 root=ubi0:rootfs0 rootfstyp
noinitrd console=ttyAM0,115200 fec_mac=00:08:02:6B:A3:1A root=/dev/n
noinitrd console=ttyAM0,115200 root=/dev/ram0 rdinit=/sbin/init fec_
[ ] ltp_imx
[ ] uuc
[ ] *theros-wifi
[*] Freescale Multimedia Plugins/Codecs --->
--- Common package selection list
[ ] *sterisk
v(+)
```

<Select> < Exit > < Help >

Select codecs you want to add.

```

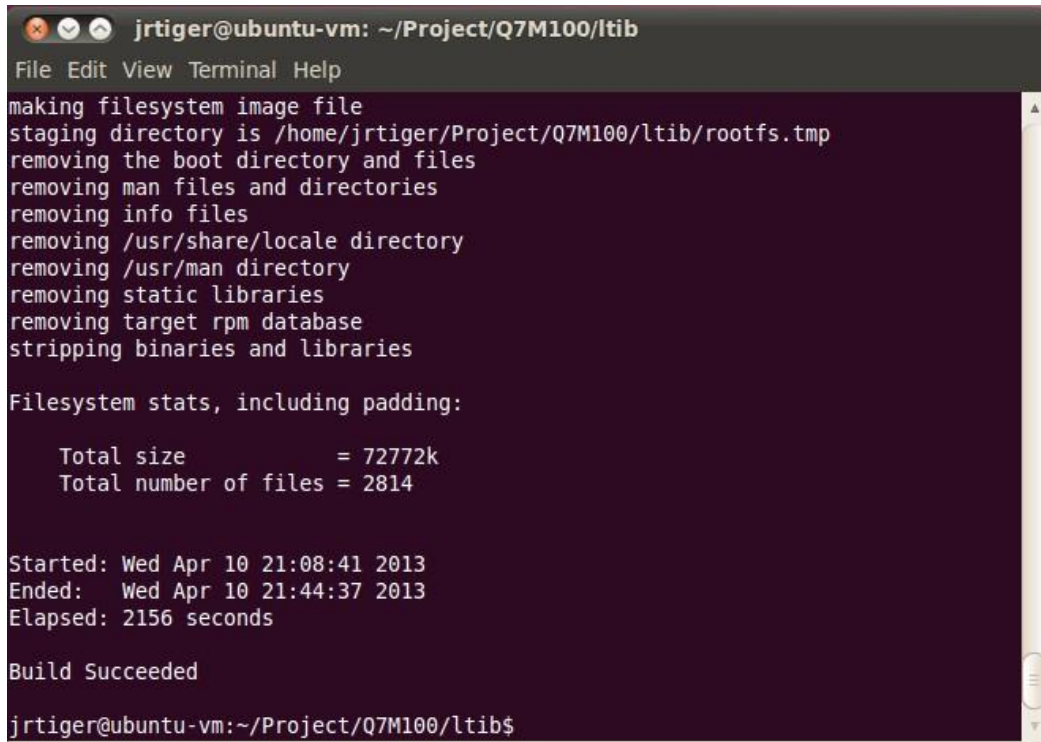
jrtiger@ubuntu-vm: ~/Project/Q7M100/ltib
File Edit View Terminal Help

Freescale Multimedia Plugins/Codecs
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing <Y> selects a feature,
while <N> will exclude a feature. Press <Esc><Esc> to exit, <?> for
Help. Legend: [*] feature is selected [ ] feature is excluded

--- [*] sl-mm-codec-libs
[ ] sl-mm-ms-codec-libs
[ ] sl-mm-aacpdec-codec-libs
[ ] sl-mm-mp3enc-codec-libs
[ ] sl-mm-ac3dec-codec-libs
[ ] sl-mm-flv-codec-libs
[ ] sl-mm-excluded-codec-libs
[*] gststreamer-fsl-plugins
```

<Select> < Exit > < Help >

9. Build the target kernel image and root filesystem.
\$ cd ~/Project/Q7M100/ltib
\$./ltib



```
jrtiger@ubuntu-vm: ~/Project/Q7M100/ltib
File Edit View Terminal Help
making filesystem image file
staging directory is /home/jrtiger/Project/Q7M100/ltib/rootfs.tmp
removing the boot directory and files
removing man files and directories
removing info files
removing /usr/share/locale directory
removing /usr/man directory
removing static libraries
removing target rpm database
stripping binaries and libraries

Filesystem stats, including padding:

    Total size           = 72772k
    Total number of files = 2814

Started: Wed Apr 10 21:08:41 2013
Ended:   Wed Apr 10 21:44:37 2013
Elapsed: 2156 seconds

Build Succeeded

jrtiger@ubuntu-vm:~/Project/Q7M100/ltib$
```

After you have completed a build using LTIB, you will have a target root filesystem in the *rootfs* directory inside the LTIB install directory.

Inside the *~/Project/Q7M100/ltib/rootfs/boot* directory, you can find kernel image *ulmage*.

1.3 Compile Driver and Tools

1. Compile and build driver of Q7M100 hardware IO devices.
Change to *ltib* directory.
`$ cd ~/Project/Q7M100/ltib`
Enter *ltib* shell mode (this is a developer function that provides an environment for compiling and building package).
`$./ltib -m shell`
Extract driver source to *ltib/rpm/BUILD* directory.
`LTIB> tar jxf Q7M100-axio.tar.bz2 -C rpm/BUILD/`
Change to *axio* directory.
`LTIB> cd rpm/BUILD/axio`
Build the driver module.
`LTIB> make`
Install the driver module to target root filesystem.
`LTIB> make install`
2. Compile and build Q7M100 library for IO devices (it depends on *q7m100.ko*).
Change to *ltib* directory.
`$ cd ~/Project/Q7M100/ltib`
Enter *ltib* shell mode (this is a developer function that provides an environment for compiling and building package).
`$./ltib -m shell`
Extract source to *ltib/rpm/BUILD* directory.
`LTIB> tar jxf Q7M100-q7_lib.tar.bz2 -C rpm/BUILD/`
Change to *q7_lib* directory.
`LTIB> cd rpm/BUILD/q7_lib`
Build shared library *libq7m100.so.1.0.0* and install to target root filesystem.
`LTIB> ./make-lib.sh`
Build RTC function tools.
`LTIB> ./make-test.sh`
Build EEPROM test program.
`LTIB> ./make-eprom.sh`
3. Compile and build Q7M100 tools.
Change to *ltib* directory.
`$ cd ~/Project/Q7M100/ltib`
Enter *ltib* shell mode (this is a developer function that provides an environment for compiling and building package).
`$./ltib -m shell`
Extract tools source to *ltib/rpm/BUILD* directory.
`LTIB> tar jxf Q7M100-tools.tar.bz2 -C rpm/BUILD/`
Change to tools directory.
`LTIB> cd rpm/BUILD/tools`
Build the tools.
`LTIB> make`
4. Then copy all binary file to target root filesystem you build. The root filesystem is a directory tree found under *rootfs*.

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Chapter 2

U-Boot for Q7M100

2.1 Booting the system with an NFS filesystem

By default, U-Boot is configured to boot from NFS. To boot from NFS, first you must set some configurations. Press any key to break from the boot progress and set configurations.

```
Setup TFTP server IP:
MX28 U-Boot > setenv serverip 192.168.0.100
Setup board IP address:
MX28 U-Boot > setenv ipaddr 192.168.0.5
Setup rootfs path:
MX28 U-Boot > setenv nfsroot /tools/rootfs
Setup boot delay:
MX28 U-Boot > setenv bootdelay 2
Save configurations:
MX28 U-Boot > saveenv
```

Reset the board and kernel will be launched.

2.2 Booting the system from eMMC

First you need to download kernel root filesystem through TFTP server, and install it into eMMC.

```
Setup TFTP server IP:
MX28 U-Boot > setenv serverip 192.168.0.100
Setup board IP address:
MX28 U-Boot > setenv ipaddr 192.168.0.5
Download kernel image through TFTP server
MX28 U-Boot > tftpboot ulmage
Using FEC0 device
TFTP from server 192.168.0.100; our IP address is 192.168.0.5
Filename 'ulmage'.
Load address: 0x42000000
Loading: FEC: Link is down 7809
#####
done
Bytes transferred = 2454628 (257464 hex)
Install kernel image into eMMC:
MX28 U-Boot > mxs_mmc install 0 0x42000000 0x257464 ulmage
Done: 4795 (12bb hex) sectors written at 256 (100 hex)
```

Download root filesystem through TFTP server (the file size limitation of this method is 96MB):

```
MX28 U-Boot > tftpboot rootfs.ext2
Using FEC0 device
TFTP from server 192.168.0.100; our IP address is 192.168.0.5
Filename 'rootfs.ext2'.
Load address: 0x42000000
```

```
Loading: FEC: Link is down 7809
#####
done
Bytes transferred = 74526720 (4713000 hex)
Install root filesystem into eMMC:
MX28 U-Boot > mxs_mmc install 0 0x42000000 0x4713000 rootfs
Done: 145560 (23898 hex) sectors written at 32768 (8000 hex)
Run system from eMMC:
MX28 U-Boot > run bootcmd_mmc
```



Note: We configure 1GB EXT partition for root filesystem. If you want to use full size to deploy your system, try booting from NFS filesystem and then format EXT partition. Extract filesystem and install it to EXT partition as follows:

```
Booting with NFS filesystem:
MX28 U-Boot > run bootcmd_net
Format EXT partition as EXT3:
$ mkfs.ext3 /dev/mmcbk0p3
Mount this partition:
$ mount /dev/mmcbk0p3 /mnt/src
Extract filesystem and install it to EXT partition:
$ tar jxf rootfs.tar.bz2 -C /mnt/src
Then reboot and boot it from eMMC.
```

2.3 Reference Document

- uboot_mx28.pdf
- ltib_build_host_setup.pdf